Gradient Flow Algorithms for Density Propagation in Stochastic Systems

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Problem: Density Propagation



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State Dynamics:

$$\mathrm{d}\boldsymbol{x} = -\nabla\psi(\boldsymbol{x},t)\,\mathrm{d}t + \sqrt{2\beta^{-1}}\,\mathrm{d}\boldsymbol{w}, \ \boldsymbol{x}_0 \sim \rho_0, \ \mathrm{d}\boldsymbol{w}(t) \sim \mathcal{N}(\boldsymbol{0},\boldsymbol{I}\mathrm{d}t), \ \boldsymbol{x} \in \mathbb{R}^n$$

Probability Density Function (PDF) Dynamics:

$$\frac{\partial \rho}{\partial t} = \mathcal{L}\rho := \nabla \cdot (\nabla \psi \rho) + \beta^{-1} \Delta \rho, \quad \rho(\mathbf{x}, \mathbf{0}) = \rho_0$$

What's new?

Main Idea: Solve $\frac{\partial \rho}{\partial t} = \mathcal{L}\rho, \ \rho(\mathbf{x}, 0) = \rho_0$ as gradient flow in $\mathcal{P}_2(\mathbb{R}^n)$ ρ_{k-1} $prox_{h\Phi}^{W^2}(\cdot)$ ρ_k 1 step delay

Proximal Operator: $\rho_k = \operatorname{prox}_{h\Phi}^{W^2}(\rho_{k-1}) := \operatorname{arg inf}_{\rho \in \mathcal{P}_2(\mathbb{R}^n)} \left\{ \frac{1}{2} W^2(\rho, \rho_{k-1}) + h \Phi(\rho) \right\}$

Optimal Transport Cost: $W^2(\rho, \rho_{k-1}) := \inf_{\pi \in \Pi(\rho, \rho_{k-1})} \int_{\mathbb{R}^n \times \mathbb{R}^n} c(\mathbf{x}, \mathbf{y}) d\pi(\mathbf{x}, \mathbf{y})$ **Free Energy Functional:** $\Phi(\rho) := \int_{\mathbb{R}^n} \psi \rho \, d\mathbf{x} + \beta^{-1} \int_{\mathbb{R}^n} \rho \log \rho \, d\mathbf{x}$

Gradient Flow in \mathbb{R}^n

$$rac{\mathrm{d} \boldsymbol{x}}{\mathrm{d} t} = -
abla arphi(\boldsymbol{x}), \quad \boldsymbol{x}(0) = \boldsymbol{x}_0$$

Recursion:

$$\begin{split} \mathbf{x}_{k} &= \mathbf{x}_{k-1} - h \nabla \varphi(\mathbf{x}_{k}) \\ &= \operatorname*{arg\,min}_{\mathbf{x} \in \mathbb{R}^{n}} \left\{ \frac{1}{2} \| \mathbf{x} - \mathbf{x}_{k-1} \|_{2}^{2} + h \varphi(\mathbf{x}) \right\} \\ &=: \operatorname{prox}_{h\varphi}^{\| \cdot \|_{2}}(\mathbf{x}_{k-1}) \end{split}$$

Convergence:

$$\mathbf{x}_k \to \mathbf{x}(t = kh)$$
 as $h \downarrow 0$

Gradient Flow in \mathbb{R}^n

$$\frac{\mathrm{d}\boldsymbol{x}}{\mathrm{d}t} = -\nabla \varphi(\boldsymbol{x}), \quad \boldsymbol{x}(0) = \boldsymbol{x}_0$$

Recursion:

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Convergence:

$$\mathbf{x}_k \to \mathbf{x}(t=kh)$$
 as $h \downarrow 0$

Gradient Flow in $\mathcal{P}_2(\mathbb{R}^n)$

$$\frac{\partial \rho}{\partial t} = -\nabla^{W} \Phi(\rho), \quad \rho(\mathbf{x}, \mathbf{0}) = \rho_{\mathbf{0}}$$

Recursion:

$$\rho_{k} = \rho(\cdot, t = kh)$$

$$= \operatorname*{arg\,min}_{\rho \in \mathcal{P}_{2}(\mathbb{R}^{n})} \left\{ \frac{1}{2} W^{2}(\rho, \rho_{k-1}) + h \Phi(\rho) \right\}$$

$$=: \operatorname{prox}_{h \Phi}^{W^{2}}(\rho_{k-1})$$

Convergence:

$$\rho_k \to \rho(\cdot, t = kh) \quad \text{as} \quad h \downarrow 0$$

Fixed Point Recursion

$$\mathbf{y} = e^{\frac{\boldsymbol{\lambda}_0^*}{\epsilon}h} \qquad \qquad \mathbf{z} = e^{\frac{\boldsymbol{\lambda}_1^*}{\epsilon}h}$$

Coupled Transcendental Equations in y and z

Theorem: Consider the recursion on the cone $\mathbb{R}^n_{\geq 0} \times \mathbb{R}^n_{\geq 0}$ $\boldsymbol{y} \odot (\boldsymbol{\Gamma}_k \boldsymbol{z}) = \boldsymbol{\varrho}_{k-1}, \quad \boldsymbol{z} \odot (\boldsymbol{\Gamma}_k^{\top} \boldsymbol{y}) = \boldsymbol{\xi}_{k-1} \odot \boldsymbol{z}^{-\frac{\beta\epsilon}{h}},$ Then the solution $(\boldsymbol{y}^*, \boldsymbol{z}^*)$ gives the proximal update $\boldsymbol{\varrho}_k = \boldsymbol{z}^* \odot (\boldsymbol{\Gamma}_k^{\top} \boldsymbol{y}^*)$

Algorithmic Setup



1D Linear Gaussian



2D Nonlinear Non-Gaussian



$$ho_{\infty} \propto \exp(-\beta \psi)$$

Computational Time for 2D Nonlinear Non-Gaussian



Computational time for 6 State Satellite Motion



• New algorithm for density propagation

• No spatial discretization or function approximations

• Extremely fast runtime

• Details: https://arxiv.org/pdf/1809.10844.pdf

Thank You!

2D OU Process with Non-gradient Drift



Multiplicative Noise



Mixed Conservative-Dissipative Drift

 $\begin{pmatrix} f_{x} \\ f_{y} \\ f_{z} \end{pmatrix}$

Relative motion of a satellite in geocentric orbit:

$$\begin{pmatrix} dx \\ dy \\ dz \\ dv_x \\ dv_y \\ dv_z \end{pmatrix} = \begin{pmatrix} -\frac{\mu x}{r^3} + (f_x)_{\text{pert}} - \gamma v_x \\ -\frac{\mu y}{r^3} + (f_y)_{\text{pert}} - \gamma v_y \\ -\frac{\mu z}{r^3} + (f_z)_{\text{pert}} - \gamma v_z \end{pmatrix} dt + \sqrt{2\beta^{-1}\gamma} \begin{pmatrix} 0 \\ 0 \\ dw_1 \\ dw_2 \\ dw_3 \end{pmatrix},$$

$$= \begin{pmatrix} s\theta \ c\phi \ c\theta \ c\phi \ -s\phi \\ s\theta \ s\phi \ c\theta \ s\phi \ c\phi \\ c\theta \ -s\theta \ 0 \end{pmatrix} \begin{pmatrix} \frac{k}{2r^4} (3(s\theta)^2 - 1) \\ -\frac{k}{r^5}s\theta \ c\theta \\ 0 \end{pmatrix}, k := 3J_2 R_{\text{E}}^2, \mu = \text{constant}$$